A Dynamic Individual Memory Results in Better Probability of Consensus in Animal Collectives Pratik Ingle^[1], Yohann Chemtob^[2], Simon Garnier^[2]

Introduction

In information-based decision making, individuals in a group primarily depends on the non-social information (information of the environment gathered directly by its sensors) and social information (behaviour of other individuals). Having Both information is essential to reduce the uncertainty and forms a group to reduce the risk. Individuals often rely on consensus decisions because of an opposing minority which might provoke separation.

A lot of decision-making models used Bayesian decision theory, when applied to animal behaviour, assumes that the individual has a prior opinion of the possible states of the options [1] One such model is introduced by Arganda et al. Individual observer options build their opinion about those options and then use social information to update their knowledge/beliefs about those options and make their decision. In nature, individuals do not get the luxury to observe all possible options before making a final decision. For example, an individual has to decide which new nest site or resting place to choose. But in some instances, it only has social information about new sites or past information about new sites that might be outdated. Not knowing personally about the new site at the time of decision makes it hard to build an opinion about options, In this study, we implemented a modified version of Arganda et al. (2012)[2] incorporating a dynamic individual memory component to it which results in better consensus over possible options to tacked these problems.



rule for decision making

Decision Making

Directed Graphs of the model

Spacial organization

Task Allocatio

1 Indian Institute of Science Education and Research Bhopal, Bhopal-462066, India 2 New Jersey Institute of Technology, Newark, NJ 07102, USA

? Environment Fig 1. A general decision-making rule in animal collectives. 潦 B 0.3 10 τ_x 20 30 40 50

(A)Decision making between two sites when nx and ny animals have already chosen sites x and y, respectively.

(B) The probability of choosing x in the general rule equation plotted as a function of the animals that have already chosen between the two sites, nx, and ny.



$$\frac{1}{(n_x - kn_y)} = e^{-mt})s^{-(n_x - kn_y)}$$

